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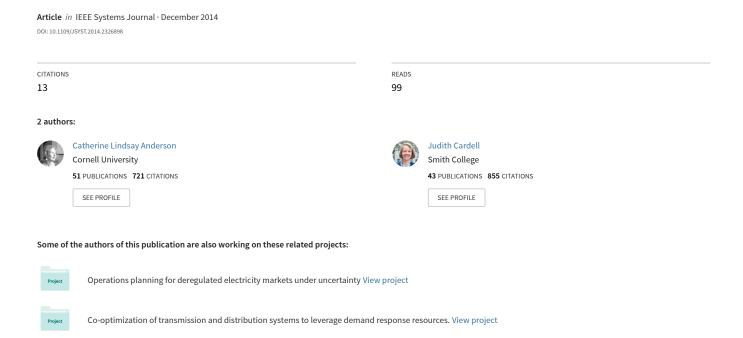
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### A Decision Framework for Optimal Pairing of Wind and Demand Response Resources



# A Decision Framework for Optimal Pairing of Wind and Demand Response Resources

C. Lindsay Anderson, Member, IEEE, and Judith B. Cardell, Member, IEEE

Abstract—Day-ahead electricity markets do not readily accom-5 modate power from intermittent resources such as wind because 6 of the scheduling difficulties presented by the uncertainty and 7 variability in these resources. Numerous entities have developed 8 methods to improve wind forecasting and thereby reduce the 9 uncertainty in a day-ahead schedule for wind power generation. 10 This paper introduces a decision framework for addressing the in-11 evitable remaining variability resulting from imperfect forecasts. 12 The framework uses a paired resource, such as demand response, 13 gas turbine, or storage, to mitigate the generation scheduling 14 errors due to wind forecast error. The methodology determines the 15 cost-effective percentage, or adjustment factor, of the forecast er-16 ror to mitigate at each successive market stage, e.g., 1 h and 10 min 17 ahead of dispatch. This framework is applicable to any wind 18 farm in a region with available pairing resources, although the 19 magnitude of adjustment factors will be specific to each region 20 as the factors are related to the statistics of the wind resource 21 and the forecast accuracy at each time period. Historical wind 22 data from New England are used to illustrate and analyze this 23 approach. Results indicate that such resource pairing via the 24 proposed decision framework will significantly reduce the need for 25 an independent system operator to procure additional balancing 26 resources when wind power participates in the markets.

27 *Index Terms*—Decision support, demand response, electricity 28 markets, wind integration, wind power.

#### I. INTRODUCTION

29

ANY states in the U.S. have passed either voluntary or mandatory requirements for a percentage of energy in their region to be served by renewable resources [1]. With hydro resources already exploited in most regions, it is assumed that wind power will be a main contributor in meeting these new standards. Although the energy generated by wind turbines is close to zero cost, nonzero costs are incurred when the power system as a whole responds to the uncertainty and variability associated with the wind resource itself. These costs arise from the need to dispatch other resources to ramp up or down to mitigate wind power deviating from its forecast output.

System analyses often focus on the costs of using the existing 42 power system and, hence, conventional technologies, such as

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gas turbines, to mitigate wind [2], [3] and to increasingly 43 include the option of storage as well. A third option is to use 44 responsive demand to mitigate the variations in wind output that 45 arise from forecasting errors. System operators are currently 46 exploring the concept of using responsive demand to mitigate 47 wind variability and for ancillary grid benefits. In particular, the 48 California Independent System Operator (CAISO) is currently 49 developing the *grid state indicators* to inform end-user response 50 decisions [4], [5].

This paper presents a methodology to reduce the net vari- 52 ability of the wind power output and to therefore allow wind 53 to participate more fully in forward markets. The proposed 54 methodology uses power generation forecasts 1 h and 10 min 55 ahead of dispatch. These forecasts are compared, successively, 56 to the submitted day-ahead schedule to quantify the expected 57 megawatt deviation in output (i.e., the variability) for the suc- 58 ceeding time period (1 h and 10 min). The proposed framework 59 then schedules a dedicated paired resource, such as responsive 60 load or storage, to mitigate the deviation from the day-ahead 61 schedule. The optimal amount of the forecast error to be miti- 62 gated at 1 h and 10 min ahead of real time is determined through 63 the proposed methodology.

Results demonstrate that the optimum level of mitigation 65 with the paired resource is related to the relative costs of the 66 resource, the accuracy of the wind forecast, and the penalty 67 imposed for spilling wind energy. The capacity of a paired 68 resource that would be required and the costs associated with 69 the use of responsive load as the pairing resource are presented 70 in a case study.

Section II discusses the government regulations and recent 72 state-level developments related to the participation of wind 73 generation in electricity markets. Section III describes the 74 framework proposed for optimal pairing of resources with wind 75 generation. The framework is tested using Nantucket sound 76 region data, described in Section IV, and Section V quantifies 77 the capacity that would be required from each of the paired 78 resource options to maintain the net wind generation output 79 to within acceptable deviation from the submitted day-ahead 80 schedule. Section VI presents the conclusions and future work. 81

## II. WIND POWER PARTICIPATION 82 IN ELECTRICITY MARKETS 83

Electricity market structures operated by independent system 84 operators (ISOs) in the U.S. include day-ahead, hour-ahead, 85 and real-time markets, as well as an increasing number of 86 ancillary services markets. As investment in wind generation 87 grows and regional expansion plans include possibilities for 88

89 significant wind capacity, the uncertainty and variability in 90 wind generation do impose real costs on system operation 91 in terms of efficient unit commitment and through providing 92 services such as balancing and regulation.

The characteristic of uncertainty in wind generation can 94 be addressed to some extent by improving the accuracy of 95 forecasting the wind resource. To this end, the Minnesota Public 96 Utilities Commission ordered a study to investigate the impacts 97 of incorporating wind generation at the level of 20% of retail 98 electricity sales by the year 2020 [6]. For this study, sophisti-99 cated meteorological modeling was performed by WindLogics 100 [7] for 2003, 2004, and 2005. The results of this study demon-101 strated that the day-ahead forecast errors were as low as 20%. In 102 addition, the broader analysis, as performed by EnerNex, found 103 that, as spatial and geographic diversity of the wind turbine sites 104 increased, the error decreased by up to 43% [6].

A report conducted by GE Energy consulting on behalf of the 106 CAISO [8], showed that the implications of ignoring forecasts 107 were so significant that a central forecasting approach was 108 implemented. A mechanism to facilitate the use of the state-109 of-the-art wind forecasting has been implemented in Califor-110 nia through the Participating Intermittent Resource Program 111 (PIRP) [9], [10]. If the participating resources submit schedules 112 consistent with the ISO-approved forecasts, then they are not 113 subject to penalties for deviations from the forecasts. The 114 PIRP in California has been operating since August 2004, and 115 achieved cumulative average deviation of the forecast close to 116 1% by 2005 and 2009 [11].

A recent study from the New York ISO (NYISO) provides a 118 detailed analysis of the impacts of increasing wind penetration 119 on power system operations and the need for transmission 120 system expansion. The analysis is based upon serving "net 121 load," determined by subtracting the variable wind generation 122 from the variable load data series. As with many previous 123 analyses, the NYSIO study assumes wind plants will operate 124 in the markets as price takers, which allows this use of net load. 125 These state-level analyses and programs demonstrate that 126 wind forecasting decreases the uncertainty in day-ahead sched-127 ules, and when combined with flexible market structures and 128 settlements facilitate increased involvement of wind power 129 generation in the day-ahead markets.

Although, some of the inherent variability in wind generation 131 remains, even as the uncertainty is reduced. To address this 132 variability, this paper investigates pairing wind output with 133 responsive demand to reduce the variability in the net wind 134 output. On the surface, this appears similar to using a net-135 load data stream as in the NYISO study. The difference is that, 136 for the analysis presented in this paper, responsive load (not 137 the entire system load) is actively paired with wind, and both 138 are assumed to participate in the markets. Recent advances in 139 demand response that would enable this pairing are discussed 140 in earlier work from this project [12].

A contribution of the analysis presented in this paper is to 142 advance the discussion of whether wind plants can and should 143 participate fully in electricity markets. Such an assumption 144 carries with it the need to demonstrate that such participation 145 will not degrade the efficiency of the markets or harm system 146 operations. This paper demonstrates the ability of wind to

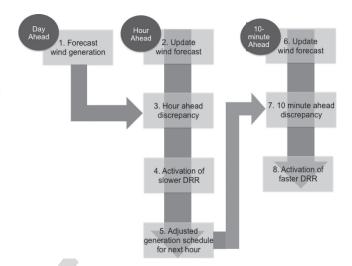


Fig. 1. Flowchart of decision structure for dispatch of paired (demand response) resource.

participate in electricity markets as facilitated by the proposed 147 method for mitigating the day-ahead schedule deviations with 148 optimized dispatch of demand response. This method addresses 149 the issue of whether wind will or should always assume a 150 passive price-taker role in electricity markets, or whether, as the 151 presence of wind increases significantly, it should have active 152 participation in more aspects of power systems and electricity 153 market operations.

#### III. FRAMEWORK FOR PAIRING WIND AND DRRS 155

The proposed framework, discussed here, determines the 156 optimal amount of a paired resource to schedule to mitigate 157 the variability in wind power generation. An important aspect 158 of the proposed framework uses updated wind forecasts at 159 each market stage to schedule the pairing resource as the 160 time horizon approaches real-time dispatch. The amount of the 161 paired resource scheduled at each time period is related to the 162 magnitude of the discrepancy between the updated forecast and 163 the day-ahead schedule.

At each time period considered, the shortfall or overshoot 165 of forecast wind production is assessed, and the need for 166 demand response or other paired resources is determined. The 167 framework is shown in Fig. 1. As shown in this flowchart, 168 the first step is to compare the day-ahead schedule to the 169 hour-ahead schedule (both discussed in more detail in the 170 following). The result of this comparison is a megawatt value 171 of generation shortfall or excess expected between the day- 172 ahead and hour-ahead schedules (see box 3 in Fig. 1). Based 173 on the magnitude of this discrepancy, a decision will be made 174 whether to activate the demand response resource (DRR) or not 175 (see box 4 in Fig. 1). The purpose of this assessment one hour 176 ahead of dispatch is to take advantage of the additional weather 177 information available and to be able to utilize slower responding 178 resources to mitigate some fraction of the expected scheduling 179 deviation. However, as further deviations are expected between 180 the hour-ahead schedule and real-time output, the paired DRR 181 will never be dispatched to meet completely the deviation be- 182 tween the day-ahead and hour-ahead schedules. The framework 183

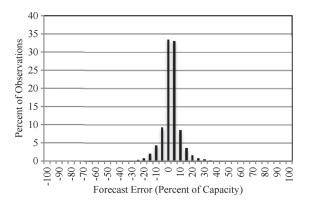


Fig. 2. Distribution of day-ahead forecast errors as percentage of capacity.

184 developed below is used to determine the optimal portion of the 185 mismatch to mitigate at each time step. The remaining excess 186 or shortfall in wind power output will be addressed with faster 187 responding demand response alternatives, to be dispatched after 188 each next-10-min forecast is made (see boxes 6–8 in Fig. 1).

189 Day-Ahead Forecast: At  $t_0$ , a day-ahead forecast determines 190 a day-ahead schedule  $G_1$  for the wind farm. For this project, an 191 autoregressive (AR) persistence model is used for forecasting 192 wind generation one day ahead, i.e.,

$$G_1 = \alpha_{24h} + \beta_{24h} P_{24h}$$

193 where  $\alpha_{24\mathrm{h}}$  and  $\beta_{24\mathrm{h}}$  are regression parameters, and  $P_{24\mathrm{h}}$  is the 194 wind generation observed 24 h ahead.

Although more sophisticated forecasting algorithms are re-196 quired for actual wind farm scheduling, for purposes of illus-197 trating the proposed framework, the linear regression model is 198 sufficient. Fig. 2 provides a sample histogram of forecast errors 199 for one year (8760 observations) as a percentage of capacity 200 for a single site in New England. The mean absolute error 201 (MAE) corresponding to these data are approximately 5%. This 202 corresponds well to the forecasting accuracy of the NYISO at 203 4.8% of the hour-ahead forecast [7].

Hour-Ahead Corrections: Although the day-ahead forecast suseful for initial scheduling, more accurate information about expected wind speed is available in the hour-ahead time frame. Although the most accurate wind speed data will not be available until 5–10 minutes ahead of actual dispatch, a first estimate of the discrepancy between the day-ahead forecast and real-time generation can be made 60–90 min ahead of real time. The correction at  $t=t_0+23$  is determined by the discrepancy  $\Delta_{1h}$ , between the day-ahead schedule and the updated hourahead forecast (determined 90 min in advance of dispatch).

Once again, an AR model is used for forecasting. At one 215 hour ahead ( $t=t_0+23$ ), the accuracy of a persistence model 216 is significantly higher than it is day ahead, i.e.,

$$\begin{split} \Delta_{1\mathrm{h}} &= G_1 - \left(\alpha_{1\mathrm{h}} + \beta_{1\mathrm{h}} P_{1\mathrm{h}}\right) \\ \mathrm{DR}_{1\mathrm{h}} &= \left\{ \begin{aligned} \Delta_{1\mathrm{h}} \gamma_{1\mathrm{h}}, & \text{if } \Delta_{1\mathrm{h}} > 0 \\ 0, & \text{otherwise} \end{aligned} \right. \end{split}$$

217 where  $DR_{1h}$  is the quantity of DRR to schedule one hour 218 ahead of dispatch, calculated from  $\gamma_{1h}$ , which is the fraction of

forecast deviation to cover with the paired resource, one hour 219 ahead.

3

A main contribution of the framework proposed here is to 221 determine the value of  $\gamma_{1h}$  (and of  $\gamma_{10 \mathrm{min}}$ , see the following) 222 that will trade off between minimizing the deviation in wind 223 generation in real time with minimizing the cost of dispatching 224 the paired resource. The case study in Section V demonstrates 225 the process for selecting  $\gamma_{1h}$  and  $\gamma_{10 \mathrm{min}}$ .

Ten-Minute Ahead Corrections: Ten minutes before the real- 227 time dispatch, a third forecast is determined. At this time, the 228 discrepancy between the hour-ahead schedule and 10-min fore- 229 casts is estimated (see box 7 in Fig. 1), where this discrepancy, 230  $\Delta_{10 \mathrm{min}}$ , is between the day-ahead schedule and the sum of the 231 10-min forecast and scheduled demand response resulting from 232 the hour-ahead forecast DR<sub>1h</sub>. This is described as follows: 233

$$\begin{split} &\Delta_{10\mathrm{min}} = G_1 - \mathrm{DR}_{1\mathrm{h}} - \left(\alpha_{10\mathrm{min}} + \beta_{10\mathrm{min}} P_{10\mathrm{min}}\right) \\ &\mathrm{DR}_{10\mathrm{min}} = \begin{cases} \Delta_{10\mathrm{min}} \gamma_{10\mathrm{min}}, & \text{if } \Delta_{10\mathrm{min}} > 0 \\ 0, & \text{otherwise} \end{cases} \end{split}$$

where  $\gamma_{10 \mathrm{min}}$  and DR<sub>10 \mathrm{min}</sub> are the fraction of forecast deviation 234 to cover and the quantity of DRR to schedule 10 min ahead, 235 respectively, (see box 8 in Fig. 1).

Minimizing Paired Resource Costs Associated With This 237 Strategy: The final step in the proposed framework uses the 238 cost of the DRRs that are utilized across all time scales. The 239 fractions of the shortfall or overgeneration to mitigate at each 240 decision point, i.e.,  $\gamma_{1h}$  and  $\gamma_{10\text{min}}$ , are estimated by minimiz- 241 ing the overall cost of paired resources in this strategy. This cost 242 is given by

$$C_T = \Delta_{1h}\gamma_{1h}C_{1h} + \Delta_{10\min}\gamma_{10\min}C_{10\min} + \Delta_{RT}C_{RT}.$$

The fractions to mitigate at both the 1-h- and 10-min-ahead time 244 horizons are determined by selecting the mitigation fractions 245  $\gamma_i$  to minimize the overall cost of the strategy. To simplify 246 notation, henceforth, the decision points will be denoted with 247 numbers [1, 2, 3] representing hour ahead, 10 min ahead, 248 and real time, respectively. Note that it is assumed that real- 249 time shortfalls are covered through procurement in the real- 250 time energy market or penalized at the real-time market price 251  $C_{\rm RT}$ . This assumption is not critical to the formulation and 252 can be altered to represent specific rules in any market under 253 consideration.

The overall framework is presented mathematically as follows: 255

$$\underset{\gamma_i, i=1, 2, 3}{\arg \min} \left[ C_T = \gamma_1 \Delta_1^+ C_1 + \gamma_2 \Delta_2^+ C_2 + \Delta_3^+ C_3 + \Delta_3^- C_P \right]$$

Subject to

$$C_{\rm RT} > C_{10{\rm min}} > C_{1{\rm h}} > 0$$
  
 $C_P \ge 0$ 

$$0 \le \gamma_i \le 1$$
, for  $i = 1, 2, 3$ .

Note that it is assumed here that  $C_{1\mathrm{h}} < C_{10\mathrm{min}} < C_{\mathrm{RT}}$ . In fact, 256 the actual costs are not important in determining the appropriate 257 mitigation fractions  $\gamma$  as long as the relative costs can be 258 estimated. Also note that overgeneration penalties can be also 259 included in this framework by defining the penalty cost for 260 overproduction as  $C_P > 0$ ; otherwise, when  $C_P = 0$ , there is 261

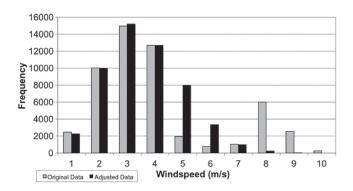


Fig. 3. Chart of time-series wind-speed data preaggregation and postaggregation algorithms.

262 no penalty for overgeneration, and the last term in the cost 263 function  $C_T$  is zero.

The following step is application of this framework to a case 265 study. For this purpose, offshore wind data from Nantucket 266 Sound in Massachusetts is selected and discussed in Section IV.

#### 267 IV. CASE STUDY REGION: NANTUCKET SOUND

To test the feasibility of this decision framework, a case study 269 of a hypothetical wind farm is presented. The wind farm is 270 modeled using data for Nantucket Sound, obtained from [13] 271 and [14] and includes wind speed measurements at 10-min 272 intervals.

To represent the aggregate output of a wind farm instead of a 274 single turbine, the effects of geographic diversity across the in-275 stallation area are considered. These effects inherently decrease 276 the variability of the wind generation and include two factors: 277 the propagation of the wind and its associated dynamic events 278 (e.g., wind gusts) through the wind farm, and the smoothing of 279 the aggregate power curve due to multiple turbines. To model 280 the decreased variability from the geographic diversity, the 281 10-min raw data are processed based on the algorithm presented 282 in [13]. Samples of the results obtained from this process are 283 presented in Figs. 3 and 4. Fig. 3 compares the distribution 284 of wind speeds before and after adjustment, and shows signif-285 icant smoothing effects for higher wind speeds, between 5 and 286 10 m/s. Fig. 4 shows the smoothing in the time series of wind 287 power generation before and after applying the aggregation 288 algorithm described in [12]. This time series is used to represent 289 the output from a hypothetical wind farm in Nantucket Sound. These figures are one example of the decreased variability in

These figures are one example of the decreased variability in wind power generation at any wind site as a result of geographic diversity.

#### 293 V. CASE STUDY RESULTS

The decision framework in Section III is then applied using the data from Nantucket Sound discussed in Section IV. The steps required for this analysis are: determination of the optimal mitigation fractions  $\gamma_{1h}$  and  $\gamma_{10 min}$ , implementation of the framework using historical data and forecasts, and analysis of cost and variability outcomes.

Note that these results do not represent a 24-h time series simulation but rather are analyses of distinct snapshots at

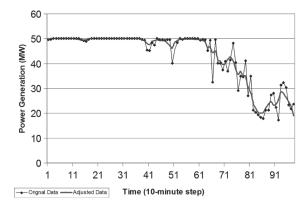


Fig. 4. Time series of wind power generation preaggregation and postaggregation algorithms.

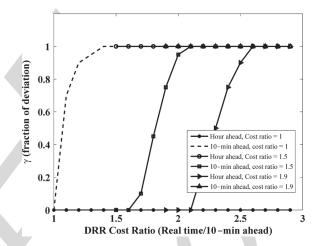


Fig. 5.  $\gamma$  values: DRR cost 10 min ahead/1 h ahead = 1.

different time steps, gradually approaching real time, with the 302 day-ahead schedule initiating the analysis, as shown in Fig. 1. 303

Determining the Mitigation Fractions,  $\gamma_T$ : In Section III, 304 the proposed decision framework was discussed as a general 305 approach. The objective of this framework is determining the 306 magnitude of the forecast error to mitigate with the alternative 307 resource at each step. These magnitudes are represented by the 308 parameter  $\gamma_T$ , where T denotes the time remaining to real-time 309 dispatch. As aforementioned, the value of  $\gamma_T$  must depend on 310 the accuracy of the forecast and the cost of the pairing resource. 311 The fact that forecast accuracy improves as T decreases (as the 312 time to dispatch gets closer) means that each  $\gamma_T$  is likely to 313 have a different value at each time horizon (T). However, faster 314 ramping resources often have higher marginal costs; therefore, 315 the cost of the pairing resource increases as T decreases.

Balancing these opposing factors is necessary to determine 317 the optimal  $\gamma_T$  value for each T and can be quantified by 318 optimization. To frame the optimization, it is not necessary 319 to know the *actual* costs of the alternative resources at each 320 T but only to know the *relative* costs. For illustration, we 321 consider a range of DRR costs and the resulting  $\gamma_T$  values. The 322 optimization is straightforward and solved in this case study 323 using Solver tool in Microsoft Excel.

Representative results from applying the equations in 325 Section III are provided in Fig. 5. This figure shows the optimal 326

5

327 mitigation fractions for hour-ahead and 10-min-ahead DRRs 328 given different ratios of real-time to hour-ahead resource costs. 329 Note that each line on the figure includes information for the 330 mitigation factor  $\gamma_T$  at both time steps, i.e., hour ahead and 331 10 min ahead, assuming any additional forecast error between 332 the 10-min-ahead time frame and real time will be mitigated 333 by the real-time resources. In Fig. 5, the x-axis represents 334 an increasing  $cost\ ratio$  for real time to hour-ahead DRRs. 335 Each line then graphs the optimal  $\gamma_T$  values for mitigating 336 wind variability first with hour-ahead DRR  $\gamma_{10}$  and then with 337 10-min-ahead DRR  $\gamma_{10}$ min. The lines differ in terms of the 338 assumed fixed ratio of 10-min-ahead to hour-ahead resource 339 costs.

The first two series (blue) in Fig. 5 depict a scenario in which 341 the cost for DRRs is the same at 1 h and 10 min ahead of 342 dispatch. In this case, the optimal  $\gamma$  values show that no DRRs 343 should be used to cover deviations at an hour ahead, i.e., the 344 line (with circles) for  $\gamma_{1h}$  is equal to zero for all real-time-to-345 hour-ahead DRR cost ratios. Since there is no additional cost 346 incurred for waiting to mitigate the wind power forecast errors 347 until 10 min ahead of the real-time dispatch, it is optimal to use 348 the more accurate forecast at 10 min before dispatch to make 349 decisions on mitigating the wind variability. It is also shown 350 in Fig. 5 that  $\gamma_{10\text{min}}$  (shown with dashed line) varies with the 351 ratio of real-time to hour-ahead DRR costs. For this scenario, in 352 which the hour-ahead and 10-min-ahead DRRs have the same 353 cost, the optimal fraction of the wind variability to mitigate 354 in the 10-min-ahead time period increases to 100% for the 355 situation in which real-time DRR costs are 150% or more of 356 the cost of hour ahead.

The third and fourth series in Fig. 5 illustrate the case of 358 a DRR that, at 10 min ahead of dispatch, demand response 359 costs are 50% more than of the hour-ahead resources. This 360 difference is significant enough to overcome the cost associated 361 with the forecast inaccuracies at 1 h ahead. In this case, the 362 expected deviation in wind generation at 1 h ahead should be 363 mitigated by the cheaper hour-ahead DRR in entirety, even with 364 the knowledge that the anticipated deviation is likely to change 365 once the improved 10-min-ahead forecast is available.

Similar to the situation in the first series, the mitigation 367 fraction at 10 min ahead  $\gamma_{10 \mathrm{min}}$  varies in a predictable way as 368 a function of the cost of real-time DRR. Initially, none of the 369 10-min-ahead DRRs are cost effective. Once the real-time costs 370 reach twice the cost of 10-min resources however, the 10-min 371 mitigation factor  $\gamma_{10 \mathrm{min}}$  reaches 100%.

Finally, the fifth and sixth series (triangles) in Fig. 5 show 373 similar results, but for the scenario in which the cost of 10-min-374 ahead DRR is nearly twice that of hour ahead resources. In 375 this situation, it is also cost effective to mitigate the entire 376 expected deviation with hour-ahead resources. In contrast to 377 the smaller cost ratio series, in this case, it is not until the cost 378 ratio for real-time to hour-ahead resources reaches 2.6 that it is 379 optimal to mitigate the entire 10-min-ahead deviation with the 380 10-min DRR.

The results presented in Fig. 5 illustrate the optimal fraction market of the wind scheduling error to be mitigated at each market stage, given different cost ratios for the DRRs that can respond in the different market time periods. These results are applicable

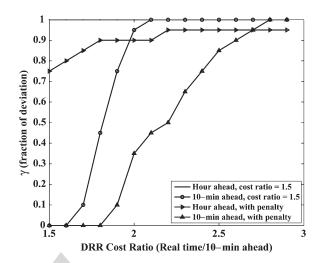


Fig. 6. Comparison with and without spillage penalty.

when there is no financial penalty associated with scheduling 385 errors.

In general, electricity market design has imposed a penalty 387 on generators that deviate more than 1.5%, for example, from 388 their schedule. This financial incentive to meet a submitted 389 schedule is consistent with the operation of dispatchable gen- 390 erators. However, it has been recognized that such penalties 391 are not consistent with the operation of generators that rely 392 on an intermittent resource such as wind since the operator of 393 such a nondispatchable generator would rarely be responsible 394 for schedule deviations. Therefore, the penalties for schedul- 395 ing deviations included in Open Access Tariffs are routinely 396 waived for wind farms, at least at the current level of low 397 penetration.

The case study presented here recognizes that the schedule 399 deviation penalties could be imposed on nondispatchable forms 400 of generation as penetration of these resources increases. The 401 case studies are not embedded in any specific market design 402 but rather include the possibility of such penalties and analyze 403 their effect.

Fig. 6 builds upon the scenario in Fig. 5 by analyzing the 405 effect of a penalty for not meeting the submitted day-ahead 406 schedule. If there were to be penalties imposed on wind gen- 407 eration for generation deviations in real time (based upon the 408 day-ahead forecast), then there would be additional financial 409 incentives to schedule a paired resource for mitigating the wind 410 variability.

Fig. 6 compares the cost-effective mitigation fractions  $\gamma_{1h}$  412 and  $\gamma_{10 \mathrm{min}}$ , when there is a penalty associated with over- 413 generation, in comparison with the same scenarios without 414 overgeneration penalty. Note that this penalty could be a direct 415 financial penalty imposed by an ISO or could be the oppor- 416 tunity cost associated with unnecessarily spilling wind that 417 appeared to be excess generation an hour or 10 min ahead of 418 dispatch.

Fig. 6 shows that with a penalty for overgeneration, the 420 hour-ahead mitigation fraction  $(\gamma_{1h})$  does not ever reach unity, 421 regardless of the fact that the resources that can respond 1 h 422 ahead are assumed to be only half the cost of the faster 423 resources that respond in the 10-min time frame. This result 424

TABLE I
ASSUMED DRR COSTS FOR NANTUCKET SOUND

Demand Response Resource	Cost (\$/MWh)
Hour Ahead	\$0.10/MWh
10 Minutes Ahead	\$0.15/MWh
Real Time	\$0.20/MWh

TABLE II  $\gamma \mbox{ Values for Three Different Mitigation Strategies}$ 

γ <sub>T</sub>	Scenario 1	Scenario 2	Scenario 3:
			$\gamma_{\rm T}$ from Figure 6
γ <sub>1h</sub>	0	0.25	0.9
<u>710M</u>	0	0.25	0.35

425 is consistent with the fact that if too much of the hour-ahead 426 DRR is scheduled, there is significant risk of incurring an 427 overgeneration penalty in real time.

428 Fig. 6 also shows that it only becomes cost effective to 429 mitigate the entire forecast error at the 10-min time frame when 430 the relative costs of real-time to hour-ahead resources reach a 431 ratio of 2.8, when an overgeneration penalty is imposed.

432 It is cost effective to cover the entire deviation at lower 433 cost ratios, for both the hour-ahead and 10-min-ahead time 434 frames, only when the wind generator is not penalized for 435 overgenerating.

436 The results for the particular  $\gamma_T$  shown here are specific 437 to the data set from Nantucket Sound, the forecasting method 438 used, and the scenarios defined in Figs. 5 and 6. The overall pat-439 tern of the results is useful for demonstrating implementation of 440 the proposed decision framework for determining the amount of 441 a paired resource to schedule for mitigating the uncertainty in 442 wind power schedules.

443 In the following section, we consider the costs associated 444 with the implementation of this strategy for the Nantucket 445 Sound case study.

Cost Results for Nantucket Sound Case Study: In consider-447 ing the benefit of using the proposed strategy for mitigating 448 wind variability, it is important to consider the availability of 449 the proposed pairing resources and the cost of implementation. 450 To this end, we analyze the outcome of the decision framework 451 using the Nantucket Sound site and DRR costs, as shown in 452 Table I. These costs are consistent with Fig. 5, and assuming 453 the real-time-to-hour-ahead cost ratio (x-axis) to be 2.0.

454 For comparing the use of the proposed decision framework to 455 two somewhat naive approaches, three scenarios with different 456 sets of gamma values are analyzed, shown in Table II.

The first scenario is the case in which no DRR used until real 458 time and the simplest approach. The second scenario represents 459 arbitrary values, as would likely be chosen if there were no 460 guiding decision framework. For this example, these values are 461 selected to bracket the gamma values that would result from 462 applying the decision framework proposed here. Thus, the third 463 set of gamma values are those obtained in Fig. 8, assuming a 464 real-time-to-hour-ahead cost ratio of 1.5.

Using this strategy, the annual usage of DRR is summarized 466 for the three scenarios (described in Table II) in Figs. 7–9. 467 These figures compare the DRR usage for each time step prior 468 to dispatch: hour ahead, ten minutes ahead, and real time.

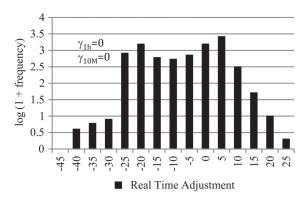


Fig. 7. Histogram of demand response usage, Scenario 1.

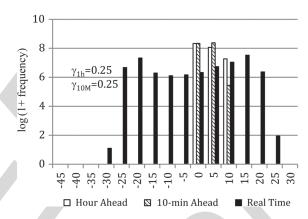


Fig. 8. Histogram of demand response usage, Scenario 2.

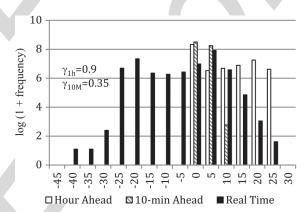


Fig. 9. Histogram of demand response usage, Scenario 3.

Fig. 10 shows a fourth scenario, when there is no penalty 469 for overproduction at the wind farm. In this case, the optimal 470 gamma variables are  $\gamma_{1h} = 1.0$  and  $\gamma_{10 min} = 0.90$ .

Figs. 7–9 show that the usage patterns of paired resources 472 have an impact on cost. Of scenarios 1–3, where there is a 473 minor penalty for overproduction, the optimal strategy (0.90, 474 0.35) is not intuitive but does produce lower overall costs for 475 covering deviations. Table III summarizes the average nonzero 476 use of DRRs (MW) at each decision point, and the cost savings 477 associated with scenarios 2, 3, and 4 relative to scenario 1. It 478 is interesting to note that, if overgeneration penalties are not 479 imposed (scenario 4), the decision framework proposed here 480 becomes even more beneficial, resulting in estimated savings 481

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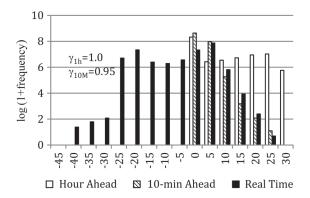


Fig. 10. Histogram of demand response usage, no overproduction penalty.

TABLE III AVERAGE DRR USE AND SAVINGS FOR NANTUCKET SOUND CASE

	MW used (*10^3)			<sup>1</sup> Cost	
Scenario	HA	10 M	Real Time		Savings (%)
			up	down	Savings (70)
1	0	0	2.5	-14	-
2	3.7	3.0	10	17	7%
3	13	1.0	3.9	16	15%
4	15	1.9	2.6	14	217%

<sup>&</sup>lt;sup>1</sup> Savings are relative to naïve strategy of mitigating 100% of deviation at each time step

TABLE IV MAXIMUM SINGLE USE OF DRR BY SCENARIO

Scenario	Maximum Single Usage (MW)			
TTD	HA	10M	RT (up)	RT (down)
1	27	22	21	45
2	6.7	5.7	23	31
3	24	7.8	22	43
4	27	21	21	44

482 of 200% of the cost of a naïve strategy of mitigating the entire 483 deviation in real time.

It is important to consider both the relative costs of these 485 strategies and the availability of this level of DRR in the 486 relevant region of New England. Therefore, in Table IV, we 487 summarize the maximum single use of DRR usage for each 488 scenario. In this table, TTD is the time to dispatch, for hour-489 ahead, 10-minute-ahead, and real-time market stages.

The size of the largest single use of DRRs at each decision 491 point is important in assessing the resources necessary for im-492 plementation of such a strategy. It appears that scenario 2 uses 493 the smallest amount of paired resource. However, comparing 494 Table III and Fig. 9 shows that real-time DRR is used very 495 frequently in this scenario. It is common in DRR contracts 496 for the number of uses to be contractually limited; therefore, 497 larger and less frequent uses might be more desirable. In the 498 case without overgeneration penalties, the average magnitude 499 of overproduction in real time is actually smaller than in other 500 scenarios; however, data in Table IV shows that there are a small 501 number of overgeneration events that are larger than in the other 502 scenarios. The optimal balance depends on the specific DRR 503 contracts of the region, and as a result, the optimal gamma 504 values should be quantitatively determined on a case-by-case 505 basis. It is also important to note that the error distributions can 506 be nonstationary, particularly with a basic forecast model such 507 as the one implemented here. The use of more sophisticated

(and proprietary) forecasting models will result in more reliable 508 error statistics and therefore more confidence in the optimal 509 mitigation fractions estimated. 510

#### VI. CONCLUSION

In general, the uncertainty and variability in load is accepted 512 as the basis for power system operations. These same charac- 513 teristics in the wind resource raise significant obstacles for the 514 integration of wind power generation into system and market 515 operations. This paper introduces an analysis of pairing wind 516 generation with DRRs to decrease the net variability of the wind 517 generation.

Results from the application of this decision framework to a 519 Nantucket Sound case study indicate that the balance between 520 forecasting accuracy, availability, and cost of pairing resources 521 (in this case demand response) is complex. Therefore, determi- 522 nation of the optimal level of mitigation of forecasting errors at 523 each time step must be determined quantitatively on a site-by- 524 site basis using specific forecasting methods, cost ratios, and 525 wind data.

The results demonstrate that wind power can participate 527 in day-ahead electricity markets through submitting schedules 528 with price offers and do not need to be restricted to participating 529 as price-takers. The analysis presented here also shows that the 530 imposition of penalties for overgeneration at wind farms is the 531 major contributor to the cost of the strategy. This highlights 532 the importance of market policy and rules, as well as the im- 533 portance of accurate forecasting techniques for the successful 534 implementation of wind in existing power markets and systems. 535

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