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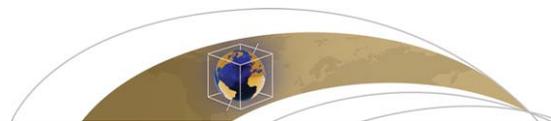
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RESEARCH ARTICLE

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Block motion changes in Japan triggered by the 2011 great Tohoku earthquake

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Key Points:

- Analytic theory for block motion changes from earthquakes
- GPS constrained block motions reveal select block motion changes before and after the 2011 Tohoku earthquake

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Abstract Plate motions are governed by equilibrium between basal and edge forces. Great earthquakes may induce differential static stress changes across tectonic plates, enabling a new equilibrium state. Here we consider the torque balance for idealized circular plates and find a simple scalar relationship for changes in relative plate speed as a function of its size, upper mantle viscosity, and coseismic stress changes. Applied to Japan, the 2011 $M_W=9.0$ Tohoku earthquake generated coseismic stresses of 10^2 – 10^5 Pa that could have induced changes in motion of small (radius ~ 100 km) crustal blocks within Honshu. Analysis of time-dependent GPS velocities, with corrections for earthquake cycle effects, reveals that plate speeds may have changed by up to ~ 3 mm/yr between ~ 3.75 year epochs bracketing this earthquake, consistent with an upper mantle viscosity of $\sim 5 \times 10^{18}$ Pa-s, suggesting that great earthquakes may modulate motions of proximal crustal blocks at frequencies as high as 10^{-8} Hz.

1. Introduction

Plate tectonic theory provides a kinematic framework for describing crustal motion at the Earth's surface. Rates of motion for the largest tectonic plates have been inferred independently over million-year time-scales from geologic observations [DeMets *et al.*, 1990] and decadal time-scales from geodetic measurements [Sella *et al.*, 2002]. In many cases, late-Cenozoic and decadal plate motion estimates agree to within 5% [DeMets and Dixon, 1999], however ~ 1 million year reorganization events have also been observed [Croon *et al.*, 2008]. At smaller spatial scales (1000 km) and shorter temporal scales ($<10,000$ years), earthquake and fault activity at some plate boundaries has also been found to be irregular in time [Bennett *et al.*, 2004; Dolan *et al.*, 2007, 2016]. A hypothesis that may provide an explanation for such short-term (subdecadal) variations is that plate motions may be perturbed over short-time scales due to changes in the crustal and upper mantle stress state caused by great earthquakes [Anderson, 1975; Romanowicz, 1993] or evolving earthquake sequences [Ismail-Zadeh *et al.*, 1999, 2007]. A geodetically based inference of accelerated Pacific plate subduction following the 2011 Tohoku, Japan earthquake may provide an example of the direct observation of this type of behavior [Heki and Mitsui, 2013]. Though this interpretation is nonunique [Tomita *et al.*, 2015], it is consistent with the inference of accelerated subduction rates beneath Kanto inferred from repeating earthquakes [Uchida *et al.*, 2016]. However, because stress changes are largest in the immediate vicinity of a great earthquake, possible changes in motion are likely to be observed in crustal blocks adjacent to the source. In particular, small tectonic plates or crustal blocks in the hanging wall above subduction zones may experience relatively large coseismic stress changes (10^2 – 10^5 Pa) along their edges with relatively little resistance to motion at the crust-mantle interface due to the fact that viscosities may be relatively low in subduction zone mantle wedges [Billen and Gurnis, 2001; Kelemen *et al.*, 2003], resulting in a coseismically induced change in plate motion.

Here we consider this argument quantitatively by calculating a first-order approximation of the magnitude of the crustal block motion change induced by coseismic stress changes using a simple disk geometry for crustal plates and assuming a Newtonian mantle rheology. These first-order predictions can be tested against geodetically constrained estimates of velocity changes before and after both the 2003 $M_W=8.3$ Tokachi and 2011 $M_W=9.0$ Tohoku earthquakes in Japan.

A challenge to the direct observation of such motion changes near major plate boundaries is that geodetically observed surface motions reflect the combined, and correlated, contributions from both plate motions

and earthquake cycle processes. In other words, interseismic strain accumulation, postseismic deformation, and plate rotations must be disentangled in the vicinity of large earthquakes. Here we utilize results from time-dependent block models of Japan that simultaneously consider these contributions in a way that minimizes temporal variations in nominally interseismic station velocity changes [Loveless and Meade, 2016].

2. Coseismic Stress and Plate Motion Changes

The motions of tectonic plates are in quasistatic force equilibrium if there is no angular acceleration and the sum of applied torques equals zero. The quasistatic torques may be partitioned into edge, T_E , and basal, T_B , components [Solomon and Sleep, 1974; Forsyth and Uyeda, 1975; Iaffaldano and Bunge, 2015] as,

$$\int \mathbf{T}_E da_E + \int \mathbf{T}_B da_B = 0, \quad (1)$$

with $\mathbf{T}_E = \mathbf{x} \times (\boldsymbol{\sigma}_E \cdot \mathbf{n}_E)$ and $\mathbf{T}_B = \mathbf{x} \times (\boldsymbol{\sigma}_B \cdot \mathbf{n}_B)$. Here \mathbf{x} is position, $\boldsymbol{\sigma}_E$ is the stress at the seismogenic edges of the block, $\boldsymbol{\sigma}_B$ is the viscous stress exerted by the mantle on the base of the block, \mathbf{n}_E is a unit vector normal to the fault at the block edge, and \mathbf{n}_B is a unit vector normal to the fault at the block base. The viscous stresses for an isoviscous Newtonian mantle are $\boldsymbol{\sigma}_B = \eta \dot{\boldsymbol{\epsilon}}_B$, where, η is the viscosity of the mantle and $\dot{\boldsymbol{\epsilon}}_B$ is the strain rate at the base of the tectonic plate. We calculate the relative magnitudes of these torques considering the case of a plate with the shape of circular disk with radius r and bounding faults extending from the surface to depth, h . A first-order approximation of the magnitude of the edge torque, T_E , is given by,

$$T_E = \left\| \int \mathbf{x} \times (\boldsymbol{\sigma}_E \cdot \mathbf{n}_E) da_E \right\| = R \|\boldsymbol{\sigma}_E\| A_E = 2\pi R r h \sigma_E, \quad (2)$$

where R is the radius of the Earth, the area of the plate edge is $A_E = 2\pi r h$, and $\|\boldsymbol{\sigma}_E\|$ gives the average stress on the edges of the plate. Similarly, a first-order approximation of the magnitude of the basal torque, T_B , is given by,

$$T_B = \left\| \int \mathbf{x} \times (\boldsymbol{\sigma}_B \cdot \mathbf{n}_B) da_B \right\| = R \eta \|\dot{\boldsymbol{\epsilon}}_B\| A_B = \frac{\pi R r^2 \eta s}{D}, \quad (3)$$

where the basal area of the plate is $A_B = \pi r^2$ and the strain rate in the upper mantle, $\dot{\boldsymbol{\epsilon}}_B$, is given by the plate speed, s , divided by the thickness of an upper mantle-like layer, D , in the Couette flow approximation. Because we are concerned with the case where the quasistatic torque balance is satisfied, both before and after a coseismic stress change, we assume that any time variation is balanced and plate geometry fixed,

$$\frac{d}{dt} (T_E + T_B) = 2h \frac{d\sigma_E}{dt} + \frac{\eta r}{D} \frac{ds}{dt} = 0. \quad (4)$$

Discretizing over finite changes in coseismic stress, $d\sigma_E/dt \approx \Delta\sigma_E/\Delta t$, and plate speed, $ds/dt \approx \Delta s/\Delta t$, the change in plate speed as a function of coseismic stress changes is,

$$\Delta s = \frac{2hD\Delta\sigma_E}{\eta r}, \quad (5)$$

which may be interpreted as the change in plate speed, without regard to change in direction, as a result of coseismic stress changes in the upper crust. In this idealized quasistatic formulation, the change in plate velocity occurs over seismic wave propagation time scales, temporally coincident with the change in coseismic stress. We can estimate the potential magnitude of this effect with characteristic parameters, $h = 15$ km, $D = 100$ km. Upper mantle viscosities beneath Japan have been estimated independently from studies of both postglacial and postseismic rebound and range from 4×10^{18} to 5×10^{20} Pa·s (Table 1) [Nur and Mavko, 1974; Nakada, 1986; Nakada et al., 1991; Suito and Hirahara, 1999; Ueda et al., 2003; Nyst et al., 2006; Mavrommatis et al., 2014]. In general, viscosity estimates at shorter forcing frequencies (100–1000 year earthquake cycles) are $\sim 10\times$ lower than those inferred at longer duration forcing frequencies ($\sim 100,000$ year glacial cycles). For intermediate field stress drops (10^2 – 10^5 Pa) associated with the Tohoku earthquake [Toda et al., 2011] and crustal blocks of radius 30 km, we estimate coseismically induced plate

Table 1. Upper Mantle Viscosity (Assuming a Maxwell Viscoelastic Rheology) Estimates in Japan From Studies of Both Postseismic and Postglacial Rebound^a

Study	Viscosity (Pa-s)	Model Type	Data Type
Nur and Mavko [1974]	5.0×10^{18}	Postseismic	Coastlines
Nakada [1986]	4.0×10^{20}	Postglacial	Coastlines
Suito and Hirara [1999]	9.3×10^{18}	Postseismic	Leveling
Nakada et al. [1991]	2.0×10^{19}	Postglacial	Coastlines
Ueda et al. [2003]	4.0×10^{18}	Postseismic	GPS
Nyst et al. [2006]	1.4×10^{19}	Postseismic	GPS
Mavrommatis et al. [2014]	5.0×10^{18}	Postseismic	GPS

^aViscosity estimates from postglacial rebound studies are 1.5–80 times larger than those from postseismic studies.

speed changes of ranging from 0.05 to 5.0 mm/yr (Figure 1). A weakness of this scalar approach is that it only reflects changes in plate speed relative to a fixed point in the mantle. What this means is that there are cases where changes in plate velocity would not be captured with this theory. For example, if a plate were moving at 5 mm/yr to the north before an earthquake and then 5 mm/yr to the south after the earthquake, $\Delta s=0$, yet the change in plate velocity is 10 mm/yr. The full tensor version of the theory addresses this issue but is beyond the scope of this paper.

3. Block Speed Changes in Japan

Due to the fact that GPS observations record not only plate motions but also earthquake cycle processes, the detection of plate motion changes requires an estimate of the relative contributions of these two effects. Previous work on the decomposition and block modeling of ~19 years of time-dependent GPS positions in Japan [Loveless and Meade, 2016] has led to the development of minimally variable velocity fields over five temporally distinct year-long epochs (Table 2). The multiyear duration of these epochs is longer than the subhourly time scale involved in the idealized quasistatic plate motion change theory described above. The reason for this is that these epochs are bracketed by specific seismic events, enabling comparison with coseismically imposed stress change, and are long enough that they can be decomposed into constitutive parts. In this work we assumed that, over each epoch, the GPS position time series at each station can be decomposed into four contributions: (1) linear trend (epoch velocity), (2) step function (coseismic displacements and equipment maintenance), (3) harmonic terms (annual and biannual signals), and (4) two exponentially decaying terms (accounting for short and long-term post-seismic deformation). Epoch velocities estimated over these intervals are determined in way that is minimally variable in the sense that the relaxation timescale for the longer exponential term is determined so that the linear terms, which we take to represent nominally interseismic velocity fields, are as similar as possible from one epoch to the next.

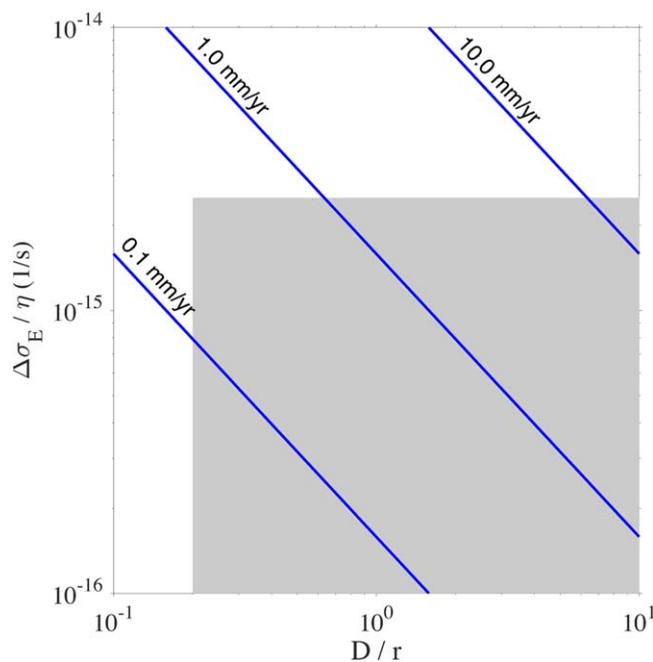


Figure 1. Blue lines show predicted changes in speed, Δs , of crustal blocks as a function of coseismic stress change, $\Delta\sigma_E$, block radius, r , depth to fixed mantle, D , and upper mantle viscosity, η . Upper plate thickness is assumed to be $h = 15$ km. Over the parameter ranges applicable to Japan (gray region), block speed changes range from 0–10 mm/yr.

These interseismic velocity fields are used as inputs into block models that

Table 2. Temporal Decomposition of GPS Displacement Time Series into ~3.75 Year Long Epochs [Loveless and Meade, 2016]^a

Epoch	Start Date	End Date	Duration (Years)
E_1	1 Apr 1996	31 Dec 1999	3.75
E_2	1 Jan 2000	24 Sep 2003	3.73
E_3	25 Sep 2003	30 Jun 2007	3.77
E_4	1 Jul 2007	10 Mar 2011	3.69
E_5	11 Mar 2011	31 Dec 2014	3.81

^aEpochs E_2 and E_4 end the day before the Tokachi and Tohoku earthquakes, respectively.

simultaneously decompose block motions from earthquake cycle effects due to coupling on block-bounding faults and the subduction interfaces off the Pacific coast of Japan (Figure 2). It is the velocity component arising from block motions, rather than the raw GPS velocities, that we consider here for the identification of changes in plate speeds, Δs . In other words, changes in plate motions are determined by considering epoch-to-epoch differences in the estimates of block rotations derived from block model decomposition of

the minimally variable GPS velocity fields. These changes in estimated rotation vectors (Euler poles) form the basis for this analysis. Instead of describing the change in motion of each block with a single scalar speed, we consider a frequency distribution of velocities by calculating differential velocities at 1000 randomly sampled geographic locations on each block (Figure 3). This approach allows us to simply see spatially complex behaviors such as those arising from local Euler poles, which are manifest as frequency distributions with large spreads (e.g., > 6 mm/yr, Figure 3).

Differential epoch-to-epoch block speeds are given by, $\Delta s_i = |\langle s(E_{i+1}) \rangle - \langle s(E_i) \rangle|$, where $\langle s(E_i) \rangle$ is the mean of the frequency distribution of location-by-location velocity during the epoch E_i (Table 2). To determine if there are distinct changes in block motions associated with the geodetic observation epochs bracketing the 2003 Tokachi and 2011 Tohoku earthquakes, we define a block speed change index. This index evaluates as true for a given block if all three speed change conditions are met. First, the mean epoch-to-epoch speed change is greater than 5 mm/yr, $\langle \Delta s_i \rangle > 5$. This criterion identifies only the largest plate motion changes. Second, the variability of differential speeds calculated at points on a given block is less than 4 mm/yr, i.e., $SD(\Delta s_i) < 4$. These criteria limit the misidentification of block motion changes that are due to local rotation rate changes. We exclude these cases because the scalar theory only represents changes in plate speed. Third, the average epoch-to-epoch variability is less than 4 mm/yr, i.e., $\langle SD(\Delta s_i) \rangle < 4$. This criterion precludes the misidentification of velocity changes in noisy regions. These three criteria are evaluated for each of the upper plate blocks in Japan.

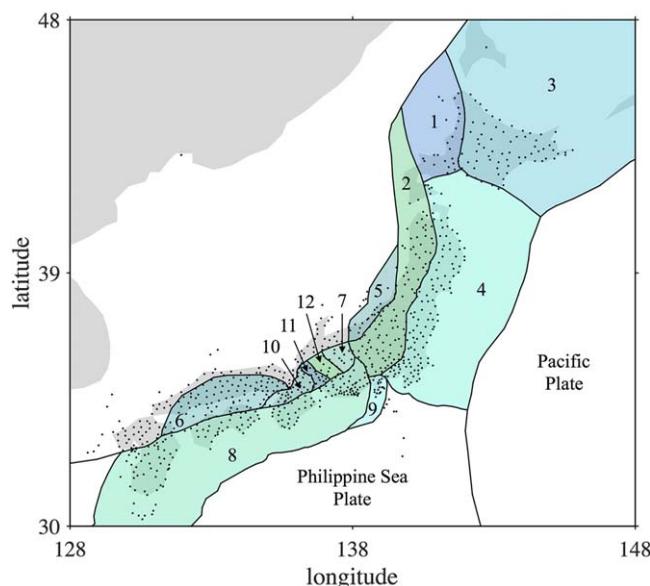


Figure 2. Japan block model geometry [Loveless and Meade, 2016] and GPS station locations (black circles). The numbers indicated here correspond to upper plate blocks referenced in Figure 3. Shading is distinct for each block considered in this study.

Using these motion change detection criteria, we find no significant epoch-to-epoch speed changes other than between the intervals spanning the 2011 Tohoku earthquake. This includes a lack of identifiable plate speed changes in the epochs bracketing the 2003 Tokachi earthquake, which may be explained by the facts that there appear to be no small crustal blocks in the immediate vicinity of this event (Hokkaido and northern Honshu) where the coseismic stress changes were largest, and the magnitude of stress change was smaller than that due to the 2011 event. In contrast, we detect four blocks that appear to have discernable changes in plate speed in the epoch bracketing the 2011 Tohoku earthquake (Figure 3). Each of these blocks lies in central Honshu near the Itoigawa-Shizuoka tectonic line and Niigata-Kobe tectonic zone and has a

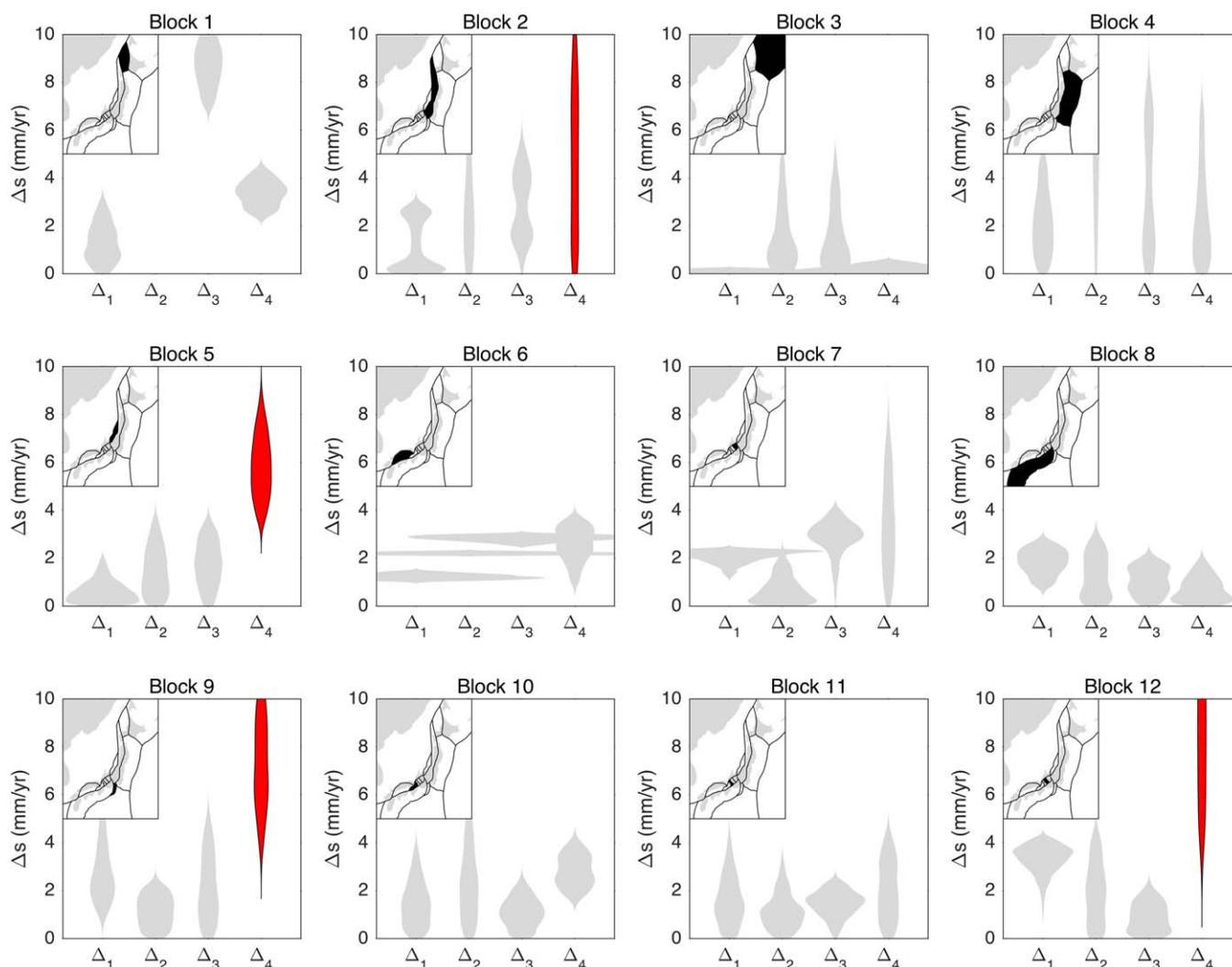


Figure 3. Epoch-to-epoch speed changes, $\Delta s_j = |\langle s(E_{i+1}) \rangle - \langle s(E_i) \rangle|$, for the Japan crustal blocks shown in Figure 2. Five, ~ 3.75 year epochs are defined over the interval April 1996 to December 2014 (Table 2). The probability density functions show the range of plate speed changes and are shaded red if the change detection index satisfies three threshold criteria and gray otherwise. Inset figures show the greater Japan region with the current block shaded black. Epoch-to-epoch speed changes satisfy the change detection index in only the Δ_4 interval (bracketing the Tohoku earthquake) for blocks 2, 5, 9, and 12 in central Honshu.

characteristic length scale of ~ 100 km. The differential speed estimates for these blocks range from 2–5 mm/yr, assuming upper mantle viscosities $> 10^{18}$ Pa·s (Figure 1). Note that the change detection index does not identify plate motion changes in the block immediately above the rupture area of the Tohoku earthquake in eastern Honshu where geodetic observations suggest that postseismic deformation is greatest [Ozawa *et al.*, 2011].

4. Discussion

Slip on geometrically complex fault systems enables tectonic plates to move past one another. At these interfaces, fault system geometry may evolve in response to geometric [Gabrielov *et al.*, 1996] and kinematic [McKenzie and Morgan, 1969] inconsistencies generated by repeated fault slip and cumulative fault offset. Similarly, fault slip rates are governed by the quasistatic equilibrium that sets the differential motion of bounding tectonic blocks. At longer time scales (> 1 million year), changes in plate motion have been ascribed to changes in the relative buoyancy of subducted geometry/material as well as the collision and growth of tectonic terranes [Iaffaldano *et al.*, 2006; Jagoutz *et al.*, 2015; Faccenna *et al.*, 2012; Iaffaldano and Lambeck, 2014]. At 1000–100,000 year time scales, emerging geological evidence suggests that rates of local

fault system activity may vary significantly (3–10×) in both strike-slip and thrust faulting environments [Dolan et al., 2016; Saint-Carlier et al., 2016]. Here we consider the possibility that short-term changes in fault slip rates may be the result of short-term changes in plate motions caused by coseismic stress changes. In other words, these observable changes in fault slip rates may be due to changes in the differential motion of bounding tectonic plates. This hypothesis provides an intrinsic source of variations in rates of fault system activity, with the implication that coseismically induced block motion changes persist sufficiently long to be captured in geologic records.

Here we have considered the case where coseismic stress changes modulate plate motions. However, this is an inherently incomplete description of potential changes in plate motions even in the narrow context earthquake cycle behaviors. For example, the time-varying effects of viscoelastic postseismic deformation may spread over 100s–1000s of km [Pollitz et al., 1998]. Time-dependent viscous deformation of the upper mantle could therefore cause accelerated or decelerated surface velocities across an entire plate, blurring the conceptual distinction between classes of models other than the fact that the viscoelastic effect would decay with time and the coseismic stress-based model discussed here would be a more discrete change in plate motions. The viscoelastic explanation appears to be most in line with the previous suggestions of changing tectonic plate motions [Anderson, 1975; Romanowicz, 1993; Pollitz et al., 1998] while the latter explanation is most consistent with ideas about fault and block systems [Gabrielov et al., 1996; Ismail-Zadeh et al., 1999]. An additional aliasing is possible when considering both coseismic displacements and changes in block motion to be step-like in time. This may be considered a simplification of the idealized version of the theory presented here and a more temporally complex type of behavior may be plausible where evolving stresses throughout the earthquake cycle modulate block and plate motions more gradually.

For the Japan example considered here, the epoch-wise velocity fields used in the block models [Loveless and Meade, 2016] were estimated after subtracting out annual and semiannual harmonics, coseismic displacements of up to 200 earthquakes, and two exponential terms (short and long-duration) following seven major earthquakes during the time span considered. If these exponentially decaying terms are interpreted as representing all postseismic deformation, then the block motion changes estimated here can be interpreted as uniquely distinguished from crustal deformation that is driven by viscoelastic or after slip processes. Similarly, the observation that the block motion change index used here does not identify the large blocks closest to the 2011 Tohoku earthquake may indicate that there is minimal aliasing between changes in block motion and more classical postseismic deformation processes. However, there is significant covariance in velocity field decomposition between the estimated linear velocity and duration of postseismic deformation even when temporal variations in the nominally interseismic velocity term are minimized [Loveless and Meade, 2016]. The use of such velocity fields in the coseismic block motion change theory

described here may therefore be considered to represent a parsimonious end-member interpretation.

In addition to this solid-earth focused hypothesis for rapid plate and fault motion evolution, climatically driven changes in surface loading have also been suggested to modulate fault slip rates [Hetzel and Hampel, 2005; Luttrell et al., 2007]. Taken together there appears to be a growing suite of mechanisms that can modulate the rates of fault system behavior over relatively short time intervals including not only slip rate variations but also changes in interseismic loading rates [Sieh et al., 2008]. These processes may contribute to understanding of short-term fault and plate motion rate changes as well as contribute to an

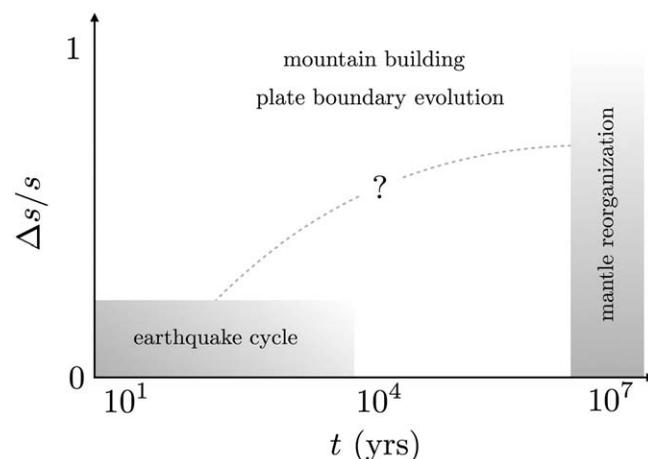


Figure 4. Schematic diagram of sources of plate motion variations, $\Delta s/s$, as a function of time, t . Shaded regions represent constraints from the earthquake cycle component described in this paper. The short-time scale variations suggested in this paper are at high-frequencies, 10^{-8} Hz, relative to mantle reorganization frequencies, 10^{-15} Hz.

emerging view of tectonic motions as noisy trends through time (Figure 4), where short-term (as low as 10^{-8} Hz) variations in fault system activity due to earthquakes and changes in surface loading lead to perturbations to long-term behavior. Whether or not a cluster of large earthquakes in a given region might change plate motions constructively or destructively over a large area remains an extant question.

5. Conclusions

The equilibrium torque balance on tectonic plates at short-length scales (<500 km) suggests that plate speeds may be moderately perturbed (<5 mm/yr) by large coseismic stress changes (10^3 Pa) if the mantle beneath the crust is characterized by a relatively low viscosity (< 10^{19} Pa-s). Following the 2011 $M_W = 9.0$ Tohoku earthquake in Japan, we identify possible motion changes (2–4 mm/yr) in four small upper plate blocks across central and southern Honshu. Similar effects are not observed in blocks that are larger and/or more distant from the rupture source, nor following the smaller 2003 $M_W = 8.3$ Tokachi earthquake. This coseismic perturbation to block motion contributes to growing list of candidate processes that may modulate the temporal evolution of block and fault system activity at plate boundaries.

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