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Towards a General Solution for Layout of Visual Goal Models with Actors: Supplemental Material

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APPENDIX

This document is the supplemental information for our RE'20 paper, which may be cited as

Yilin Lucy Wang and Alicia M. Grubb. Towards a General Solution for Layout of Visual Goal Models with Actors. In Proceedings of the IEEE 28th International Requirements Engineering Conference, 2020.

This document contains an excerpt of the FLAAG algorithm presented in the paper, as well as the helper functions not presented in the paper.

Algorithm 1 Excerpt of FLAAG: Actor-based Goal Model Layout

Require:

Goal Model $M = \langle A, G, R \rangle$
Constants C_A, C_N, C_M \triangleright Constants for Actors, Nodes, and Moves.
Maximum Layout Iterations $maxItr$ \triangleright Optional Timeout
Initial Layout Information $initLay$ \triangleright Optional coord. for elements in M .

Ensure:

Final Graph Layout Information

```
1: ( $actorSet, nodeSet$ )  $\leftarrow$  INITIALIZATION( $M, initLay$ )
2:  $curCtr = 0$   $\triangleright$  Initializes iteration counter.
3: while CHECKCOND( $curCtr, actorSet, nodeSet, maxItr$ ) do
4:   for  $node \in nodeSet$  do
5:     ADJUST( $node, actorSet, nodeSet, False, C_A, C_N, C_M$ )
6:   for  $actor \in actorSet$  do
7:     ADJUST( $actor, actorSet, nodeSet, True, C_A, C_N, C_M$ )
8:    $curCtr++$ 
9: SETCOORDINATEPOSITIVE( $nodeSet$ )
10: GETSIZEOFACTOR( $actorSet, nodeSet$ )
11: CALCULATEACTORPOSWITHREC( $actorSet$ )
12: MOVENODESTOABSPOS( $actorSet, nodeSet$ )
13: return ( $actorSet, nodeSet$ )
```

Here we describe the helper functions listed on Lines 9–12 of Algo. 1. We use these helper functions after the relative positions are established for each actor and intention (i.e., nodes). Some of the relative coordinates that are generated by the force-directed algorithm are negative numbers. Since we calculate positions of intentions within actors from the upper left corner, Algo. 2 sets the relative coordinates to positive numbers. Algo. 2 takes in the $nodeSet$ and assigns the coordinates of each node to positive numbers by adding the largest absolute value of the coordinates.

Next, Algo. 3 calculates the width and height of each actor by determining the differences between the largest and smallest values for the node coordinates that belong to the actor. Algo. 3 takes in the actor and the coordinates of the intentions in each of the actors. Using this information, Algo. 4 finds the final positions for the actors by first sorting the x coordinate and then sort the y coordinate of each actor. The arrangement of the actors is completed from the upper left to the bottom right, where subsequent actors are placed at the bottom right of the previous actor. Finally, Algo. 5 finds the final position for the nodes by adding the x coordinate and y coordinate of the actor, to which the node belongs, to the relative coordinates of each node.

Algorithm 2 SETCOORDINATEPOSITIVE Helper Function

```
1: function SETCOORDINATEPOSITIVE( $nodeSet$ )
2:    $maxNXDict \leftarrow$  new dictionary
3:    $maxNYDict \leftarrow$  new dictionary
4:   for  $node \in nodeSet$  do
5:      $curActor \leftarrow node.actorId$ 
6:     if typeof $curActor = undefined$  then
7:        $maxNXDict.curActor = 0$ 
8:     if typeof $curActor = undefined$  then
9:        $maxNYDict.curActor = 0$ 
10:    if  $curX < 0$  then
11:      if  $maxNXDict.curActor > curX$  then
12:         $maxNXDict.curActor = curX$ 
13:    if  $curY < 0$  then
14:      if  $maxNYDict.curActor > curY$  then
15:         $maxNYDict.curActor = curY$ 
16:    for  $node \in nodeSet$  do
17:       $curId = node.actorId$ 
18:       $node.nodeX = node.nodeX - maxNXDict.curId$ 
19:       $node.nodeY = node.nodeY - maxNYDict.curId$ 
```

Algorithm 3 GETSIZEOFACTOR Helper Function

```
1: function GETSIZEOFACTOR(actorSet, nodeSet)
2:   maxPXDict  $\leftarrow$  new dictionary
3:   maxPYDict  $\leftarrow$  new dictionary
4:   minPXDict  $\leftarrow$  new dictionary
5:   minPYDict  $\leftarrow$  new dictionary
6:   for node  $\in$  nodeSet do
7:     curX = node.nodeX
8:     curY = node.nodeY
9:     curActor = node.parent
10:    if typeof maxPXDict.curActor = undefined then
11:      maxPXDict.curActor = 150
12:    if typeof maxPYDict.curActor = undefined then
13:      maxPYDict.curActor = 100
14:    if typeof minPXDict.curActor = undefined then
15:      minPXDict.curActor = 150
16:    if typeof minPYDict.curActor = undefined then
17:      minPYDict.curActor = 100
18:    if maxPXDict.curActor < curX then
19:      maxPXDict.curActor = curX
20:    if maxPYDict.curActor < curY then
21:      maxPYDict.curActor = curY
22:    if minPXDict.curActor > curX then
23:      minPXDict.curActor = curX
24:    if minPYDict.curActor > curY then
25:      minPYDict.curActor = curY
26:    for actor  $\in$  actorSet do
27:      actorId = actor.nodeId
28:      if typeof maxPXDict.actorId = undefined then
29:        maxPXDict.actorId = 150
30:      if typeof maxPYDict.actorId = undefined then
31:        maxPYDict.actorId = 100
32:      if typeof minPXDict.actorId = undefined then
33:        minPXDict.actorId = 0
34:      if typeof minPYDict.actorId = undefined then
35:        minPYDict.actorId = 0
36:      x = maxPXDict.actorId - minPXDict.actorId + 300
37:      x = maxPYDict.actorId - minPYDict.actorId + 200
38:      actor.sizeX = x
39:      actor.sizeY = y
```

Algorithm 4 CALCULATEACTORPOSWITHREC Helper Function

```
1: function CALCULATEACTORPOSWITHREC(actorSet)
2:   actorsXSorted = sortActorX(actorSet)
3:   actorsYSorted = sortActorY(actorSet)
4:   curX = 0
5:   curY = 0
6:   for actor  $\in$  actorsXSorted do
7:     actor.nodeX = actor.nodeX + curX
8:     curX+ = curNode.sizeX
9:   for actor  $\in$  actorsYSorted do
10:    actor.nodeY = actor.nodeY + curY
11:    curY+ = curNode.sizeY
```

Algorithm 5 MOVENODESTOABSPOS Helper Function

```
1: function MOVENODESTOABSPOS(actorSet, nodeSet)
2:   for node  $\in$  nodeSet do
3:     actorId = node.parent
4:     for actor  $\in$  actorSet do
5:       if actor.nodeId = actorId then
6:         curX = node.nodeX
7:         curY = node.nodeY
8:         node.nodeX = curX + actor.nodeX + 150
9:         node.nodeY = curY + actor.nodeY + 100
```
