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# Adding Temporal Intention Dynamics to Goal Modeling: A Position Paper

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**Abstract**—Goal models for early phase requirements enable modelers to elicit stakeholders’ intentions, analyze dependencies and select preferred alternatives. Standard analysis techniques provide options for analysis of static goal models but do not consider the dynamic environment that the model represents and do not evaluate the intentions over time. In this position paper, we illustrate that goal model analysis for early phase requirements can be improved by explicitly considering the intention dynamics of a potential system across multiple time scales.

## I. INTRODUCTION

Early-phase requirements engineering focuses on understanding the environment in which a software system exists. Goal modeling addresses the needs of stakeholders and end-users by illustrating potential scenarios, and testing phenomena. Given lower-level phenomena (which we will refer to as intentions), goal modeling is able to predict how high-level goals will be impacted by different evaluations of the intentions. Several notations have been developed for modeling goals [1] [2] [3] [4] [5]. In choosing between alternative scenarios, prior work in design-time goal modeling assumes that intention evaluations do not change once assigned, and therefore the analysis is static and unable to answer questions about what happens on different time scales and which alternative is better at a specific point in time. The goal of our project is to understand the impacts of dynamically changing intentions on decision making. Specifically, we enrich goal models with the capability of expressing intentions with dynamically changing evaluations and temporally delayed dependency relationships. Our work focuses on extending existing *i\** analysis techniques (such as *forward analysis* [6]) to predict how these changes will affect the satisfaction of high-level goals across multiple time scales. In this paper, we illustrate, by way of example, the need for analysis across multiple time scales, our framework for describing dynamic goal models, and our extension to standard goal modeling techniques.

The remainder of this paper is organized into sections. Section II introduces the motivating example and relevant background. Section III discusses how we introduce dynamic behaviour into *i\**. Section IV discusses our framework for facilitating the analysis. Section V connects our approach to related work. Finally, we conclude in Section VI.

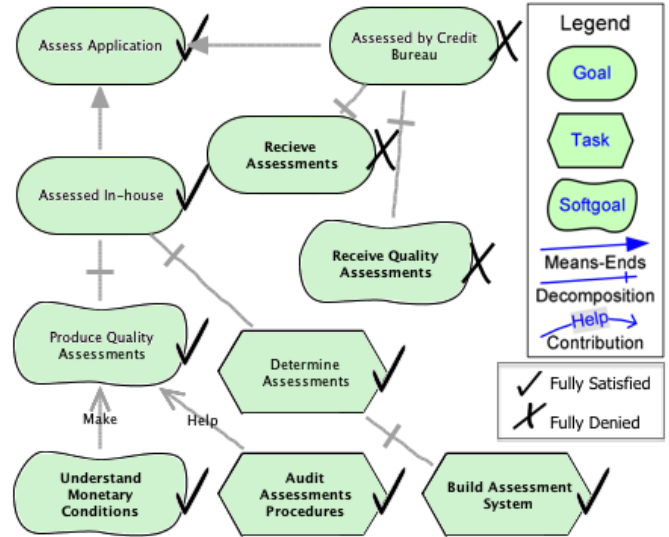


Fig. 1. Assess loan application sub-model with forward analysis performed, based on the label assignments of leaf-level intentions (in bold).

## II. BACKGROUND: FORWARD ANALYSIS & EARLY REQUIREMENTS

We introduce relevant background with an example. Consider a bank looking to enter the loan market (this example was inspired by Asnar et al. [7]<sup>1</sup>). The bank wants to develop a system to accept, assess, and approve loan applications. One key decision in this process is whether to assess the applications in-house or outsource the assessments to a credit agency. Figure 1 shows the partial *i\** goal model [1] of this decision, consisting of intentions: goals, tasks, and softgoals; and connections between the intentions: means-ends, decomposition, and contribution links (see Legend for representations of intentions and connections). The root goal *Assess Application* is OR-decomposed (represented by *Means-Ends* links) into the goals *Assessed In-house* and *Assess by Credit Bureau*. *Assess by Credit Bureau* is then AND-decomposed (represented by *Decomposition* links) into the *Recieve Assessments* goal and the *Receive Quality Assessments* softgoal. *Assessed In-house* is AND-decomposed into

<sup>1</sup>We ignore the cost of each option for simplicity.

the Produce Quality Assessments softgoal and Determine Assessments task, which is further AND-decomposed into the Build Assessment System task. Finally, Understand Monetary Conditions and Audit Assessments Procedures are connected by contribution links (affecting the satisfaction or fulfillment of a softgoal) to Produce Quality Assessments. *Makes/Helps* contribution links pass the evaluation label from the link source to the link target<sup>2</sup>.

Given our  $i^*$  model, we can evaluate the tradeoffs within Assess Application’s alternatives using current goal modeling techniques, specifically, *forward analysis* [6]. Forward analysis allows modelers to assign satisfaction evaluations to the leaf-level nodes (intentions) in a goal model and have child evaluation labels propagate up to give values to their parent node, eventually giving values to root nodes (goals). For example (as shown in Figure 1), if Understand Monetary Conditions, Audit Assessments Procedures, and Build Assessment System are assigned the value *Fully Satisfied* (or  $\checkmark$ ), and Receive Assessments and Receive Quality Assessments are assigned *Fully Denied* (or  $\times$ ), then parents Produce Quality Assessment and Determine Assessments receives the value  $\checkmark$ , and Assess by Credit Bureau receives the value  $\times$ . Next, Assessed In-house receives the value  $\checkmark$  from its children. Finally, Assess Application receives the value  $\checkmark$ . By following this propagation, the modeler can determine that the bank can satisfy its Assess Application goal by assessing the applications in-house.

Suppose instead that the modelers assigned  $\checkmark$  to Receive Assessments and Receive Quality Assessments; and assigned  $\times$  to Build Assessment System. Applying forward analysis to propagate these leaf-level values results in Assess Application obtaining the  $\checkmark$  label, only this time the satisfaction label propagates from the Assess by Credit Bureau node. From these initial values, the bank should choose to use the credit bureau for their assessments. By trying different scenarios, the modelers can understand the impacts of each tradeoff.

### III. DYNAMICALLY CHANGING INTENTIONS: SIMULATION & ANALYSIS

Standard goal modeling assumes that once an evaluation label of an intention is assigned by the modeler, it remains constant; goal modeling only discusses static models. Once a decision between the alternatives is made, it is also assumed to be static. Returning to our example, the bank is likely to determine the satisfaction of leaf-level goals based on the current situation of the bank. However, using only information about the current situation may lead to suboptimal decisions. The above analysis indicated that if the bank has an assessment

TABLE I  
DEFINITIONS OF DYNAMIC FUNCTIONS TYPES FOR INTENTIONS

Name	Definition
<i>Stochastic (RND)</i>	changes in satisfaction level are non-deterministic or random
<i>Set-Stay-Set Positive (SSS<sup>+</sup>)</i>	stochastically changing until a <i>static-state</i> of $\checkmark$ is reached
<i>Set-Stay-Set Negative (SSS<sup>-</sup>)</i>	stochastically changing until a <i>static-state</i> of $\times$ is reached
<i>Monotonic Positive (M<sup>+</sup>)</i>	its value will be “more true” or trend toward $\checkmark$ as time progresses
<i>Monotonic Negative (M<sup>-</sup>)</i>	its value will be “less true” or trend toward $\times$ as time progresses
<i>User Defined</i>	its value is a stepwise function defined by the modeler

system built (Build Assessment System labeled  $\checkmark$ ), then it should assess the applications in-house; otherwise, the bank should use the Credit Bureau to assess the applications. However, this may seem counterproductive in early-phase requirements, since it is unlikely that a bank, looking to enter the loan market, has a pre-existing assessment system but it might be willing to build one. Given it is apparent that Build Assessment System and other intentions in the model change over time, at what point should the banks decision also change. We look at the dynamics of intentions, goals, and connections both at single points in time and across time periods.

#### A. Inputs

We first consider the changes involved in modeling intentions as dynamic entities, whose satisfaction level changes over time. Returning to the decision of how to assess loan applications (Figure 1), we define several possible types of dynamic functions that can be applied to intentions in Table I and illustrate the expression of these functions in Figure 2. The *Set-Stay-Set Positive (SSS<sup>+</sup>)* function describes intentions that will become  $\checkmark$ , and once they are achieved, they stay achieved. The achievement of *SSS<sup>+</sup>* intentions can mark the end of a process, such as Build Assessment System or Receive Assessments. By making Receive Assessments *SSS<sup>+</sup>*, we are denoting that once an agreement is reached with the credit bureau, the credit bureau will continue to provide assessments. In Figure 2, Receive Assessments becomes  $\checkmark$  at  $t_1$  and remains  $\checkmark$  throughout the simulation. Build Assessment System is also modeled as *SSS<sup>+</sup>* because once the system is built, it will always remain built. The *Monotonic Positive (M<sup>+</sup>)* function is similar to *SSS<sup>+</sup>*: once the intention reaches the  $\checkmark$  state, it will stay achieved. *M<sup>+</sup>* differs from *SSS<sup>+</sup>* in that prior to this achievement, the *SSS<sup>+</sup>*’s evaluation is stochastic, whereas the *M<sup>+</sup>* intention will never decrease in satisfaction. Audit Assessments Procedures is understood to be *M<sup>+</sup>* because the procedures can be partially implemented and improved over time. In Figure 2, the monotonic progression of Audit Assessments Procedures occurs between  $t_3$  and  $t_5$ .

<sup>2</sup>Although not shown in this example, contribution links pass negative (or opposite) evaluation labels through *Breaks/Hurts*.

When intentions are known to be dynamic but their particular dynamic behaviour is unknown, we model these intentions as *Stochastic (RND)*. Understand Monetary Conditions and Receive Quality Assessments can change their values at any time, and are therefore initially modeled as *RND*. Although we have not illustrated every dynamic function type in the loan example, there are other alternatives (also denoted in Table I). *Set-Stay-Set Negative ( $SSS^-$ )* and *Monotonic Negative ( $M^-$ )* are the complementary functions to  $SSS^+$  and  $M^+$ : they progress toward and result in the final state of  $\times$  instead of  $\checkmark$ . Finally, we introduce the *User Defined* function allowing modelers to define and create their own stepwise functions, thus enabling greater flexibility in dynamic functions.

We allow modelers to constrain the order in which intentions can become satisfied. Constraints can involve known relationships between elements, such as “one happens before another” or “one changes faster than another”. For example, in Figure 2, we added the constraint that Receive Assessment must be satisfied before Receive Quality Assessment, which is encoded as  $\text{Receive Assessment} \geq \text{Receive Quality Assessment}$ .

Notice that the intention values, in Figure 2, change between  $\times$  and  $\checkmark$  at various times ( $t_0 \dots t_{11}$ ). We rely on the modeler to declare timing points of interest. For example,  $t_2$  is a notable time point because it is the first time that Assess Application is assigned a value of  $\checkmark$ . These time points mark the boundaries of epochs to reason over and enable us to answer questions such as: “what is happening now?”, “what will happen soon?”, and “what will happen in the distant future?”.

Next, we extend the standard  $i^*$  notation to enable propagation delays across links and introduce an augmented label. When the satisfaction label of a child node changes, there may be a delay in this change propagating to the parent node (indicated by a “\*” on the label). For example, a *Makes\** contribution link uses the same propagation rules as its *Makes* counterpart but with the added possibility of a delay. Referring to Figure 1, if Understand Monetary Conditions had a *Makes\** relationship with Produce Quality Assessments instead of *Makes*, then when the Understand Monetary Conditions value changes, the value of Produce Quality Assessments would not necessarily change immediately. In Figure 2, this delay in propagation is shown in the value of Produce Quality Assessments between  $t_3$ - $t_5$  and  $t_8$ - $t_9$ . Similarly, Build Assessment System is connected with Determine Assessments by a *Decomposition\** link instead of *Decomposition*. The propagation of the changes in Build Assessment System at  $t_3$  and  $t_7$  are delayed in Determine Assessments.

### B. Analysis

Given our  $i^*$  model extended with dynamic intentions and relationships described above, we can temporally extend  $i^*$  analysis over both points and functions. In this section we only discuss forward analysis, which reasons about goals given

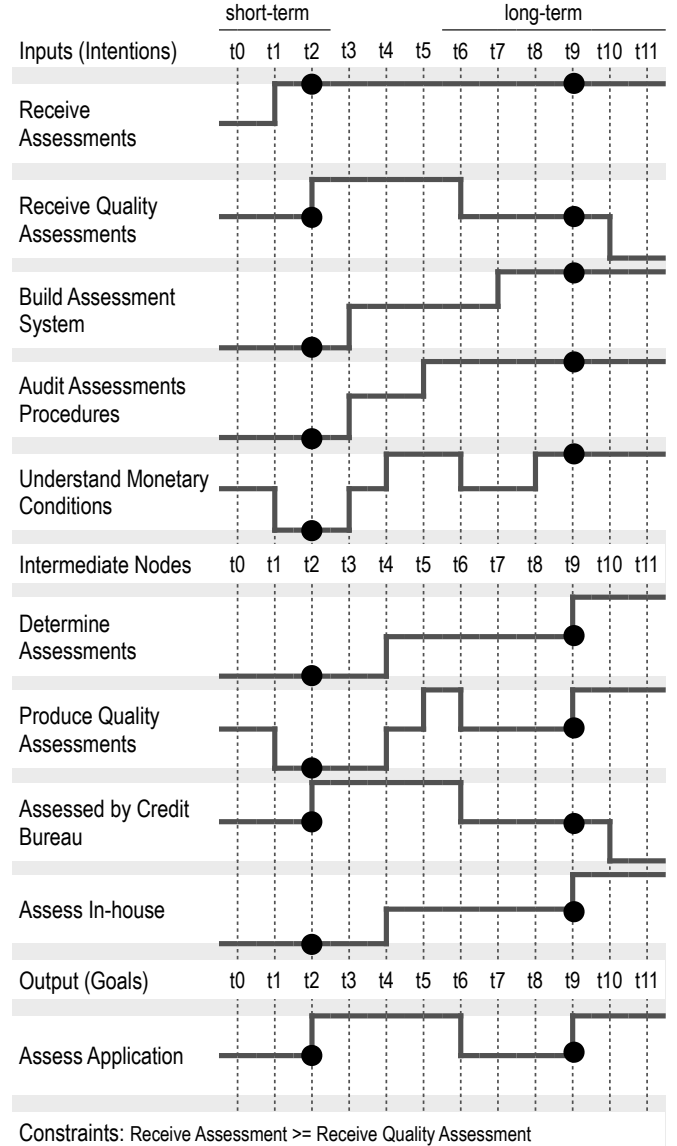


Fig. 2. A diagram of the dynamically changing intentions in Figure 1, where the three values are  $\checkmark$  (top), *Unknown* (middle), and  $\times$  (bottom). The values are propagated (using forward analysis) from the given Inputs (Intentions) through Intermediate Nodes to the Outputs (Goals). The two columns of solid ‘dots’ represent simulation at two points in time (where only a single point value is known). The solid lines for Inputs (Intentions) represent the dynamic functions given by the modeler. The solid lines for the Intermediate Nodes and Output (Goals) represent the functions computed by our propagation algorithm. The model constraints are listed at the bottom.

intentions as inputs, but the same extension can be applied to *backward analysis* [8], which uses goals to reason about intentions. We show results of both simulation and analysis for our loan example diagrammatically in Figure 2. The top five items are the leaf-level intentions (or inputs) which are propagated to the root-goal (or output). The low, middle, and high signals give the values  $\times$ , *Unknown*, and  $\checkmark$ , respectively.

We can simulate goal model satisfaction by varying leaf-level intentions and propagating their values to goals. For example, we illustrate two points of

simulation with the vertical dots in Figure 2. When Receive Quality Assessments reaches  $\checkmark$  (the left column of dots), the simulator propagates the  $\checkmark$  value up to AssessedbyCreditBureau taking into account the *Decomposition* relationship with Receive Assessments. Similarly, a second point of simulation (right column of dots) shows how simulation handles the propagation delay from the *Decomposition\** relationship between Build Assessment System and Determine Assessments (described above). By simulating these points, we can establish that both the Assess Application’s *Means-Ends* links are valid options (i.e., leading to the  $\checkmark$  evaluation for Assess Application). Through simulation, we can re-evaluate and propagate the values in the model, across many points in time or whenever there is a change in the satisfaction level of any intention in the model. While simulation is useful for visualizing possible scenarios, it is limited in its predictive power, i.e., being able to understand trends in the model.

We can analyze goal model satisfaction by using the dynamic functions of the intentions (described above) and extend forward analysis to compute the dynamic functions of the root-level goals. For example, if we again consider Build Assessment System (a  $SSS^+$  function) and propagate this with the delay described above we can compute that Determine Assessments is a  $SSS^+$  function as well with the constraint that Build Assessment System  $\geq$  Determine Assessments. We can envision manipulating the complete function for each intention (shown as a signal in Figure 2) to compute the complete function for each of the Intermediate Nodes and the Output (Goals) function.

### C. Output & Interpretation

To interpret the results of our analysis, we focus on understanding two distinct epochs (*short-term* and *long-term*); the exact number and duration of epochs are user-defined. Returning to the example, we define short-term as “until  $t_2$ ” and long-term as “after  $t_6$ ” (as shown in Figure 2). Building on the concept of epochs, we allow the modeler to assign different dynamic functions, based on stakeholder evidence, for each distinct epoch. In the short-term, Build Assessment System remains  $\times$  because the bank has not yet invested in building the assessment system. Since the system will eventually be built, Build Assessment System is modeled as  $SSS^+$  in the long-term. The bank may hire expert workers or reallocate existing employees to satisfy Understand Monetary Conditions but in the short-term, the bank will not be able to make Assessed In-house  $\checkmark$  until the bank can satisfy Determine Assessments (which is decomposed into Build Assessment System).

In the short-term, the bank may be able to hire a credit bureau making Receive Assessments  $\checkmark$ . Instead of modeling Receive Quality Assessments as  $RND$ , we could model this intention as  $M^+$  in the short-term because the bank will closely monitor and give feedback to the new partnership. Receive Quality Assessments also has a constraint that

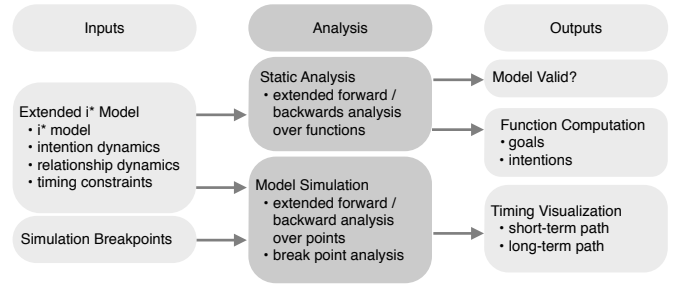


Fig. 3. System Framework

it will not become  $\checkmark$  until Receive Assessments is  $\checkmark$ . In the long-term, Receive Quality Assessment remains  $RND$ . It may become *Unknown* or  $\times$  if the integrity and quality of the credit bureau declines resulting from changing market conditions. If the bank had made its decision based solely on the short-term analysis, this decision may result in inaccurate assessments in the long-term.

Again these results are dependent on which dynamic function the modeler chooses for each intention. If the bank believed that Build Assessment System could be approximated to a  $M^+$  function then it would eventually be  $\checkmark$ , but if instead it was modeled as a  $RND$  variable, then the results would not be predictable and other scenarios should be considered. In the short-term, creating software to assess applications in-house may be more risky resulting in the external credit agency (which has a greater long-term risk) being chosen. This example allowed us to show that short-term and long-term outcomes differ and both are relevant to the decision making process.

## IV. FRAMEWORK OVERVIEW

In order to facilitate the analysis demonstrated in Section III, we designed a framework and present high-level components in Figure 3. Below, we describe the requisite components of the current framework. Work is ongoing to improve and complete these components.

### A. Inputs

We require the modeler to make the dynamic behaviour of goals in the system explicit. Our analysis takes  $i^*$  models (including initial satisfaction levels), such as the one we described in the previous sections. In addition to the standard  $i^*$  model, modelers have the option of specifying a dynamic function type (defined in Table I) for each intention as well as relationship dynamics and timing constraints. To facilitate user interactions with our simulator, we created a simple constraint language to articulate points of interest (or breakpoints) within a trace. A breakpoint can be specified as when an intention reaches a declared satisfaction level, or after a discrete number of simulation steps.

### B. Analysis

In our Model Simulation, we simulate the satisfaction of dynamic intentions with and without delayed relationships

for a given goal model over a series of time steps. Our simulation uses polling to check for changes in the model and uses extended forward analysis over points at each step to update the model. The Model Simulation outputs the Timing Visualization as both a text file (shown in Figure 4) and a signal diagram (presented in Figure 2) for a given single short-term and long-term path. The simulation output (see Figure 4) prints the information presented in the  $i^*$  input file (the intentions, goals, and their respective types and initial values). Each line of the simulation presents the intentions/goals vertically and the current satisfaction level horizontally (represented by the numbers 0 (**X**), 1 (*Partially Denied*), 2 (*Unknown*), 3 (*Partially Satisfied*) and 4 (**✓**)). The simulation stops and prints whenever a constraint or breakpoint is triggered. Finally, the simulation ends with short-term and long-term recommendations for any tradeoffs in the model.

The Static Analysis module consists of extensions to standard  $i^*$  analysis techniques across functions: forward analysis as described above, and backward analysis. We will develop constraints for the permutations of the dynamic function types and temporal relationships discussed above, to allow for the propagation of functions. We will connect our analysis with an SMT solver [9] to compute the resulting functions for a given model. If all the constraints can be satisfied, our Static Analysis will output the Function Computation for the goals (in forward analysis) and the intentions (in backward analysis), otherwise it will indicate that the model is over-constrained.

### C. Status

At this time, we have built an initial Model Simulation. We have completed the extended forward analysis over points and have incorporated some of the breakpoint analysis. We have not implemented extended backward analysis over points. Our simulator is solely text based at this time. We hope to implement a graphical interface soon. Our next step is to implement the Static Analysis initially for extended forward analysis over functions with the goal of determining the root-goal functions if the model is valid.

## V. RELATED WORK

We are not the first to investigate the temporal nature of goals. Regev and Wegmann [10] discuss how goals change in their achievement over time and classify goals into types (i.e., achievement goals, maintenance goals, softgoals, beliefs, and constraints) for the purpose of developing heuristics to improve goal identification. Achievement goals map to our  $SSS^+$  dynamic function and constraints map to  $SSS^-$ . Other goal types could be represented as *RND* or *User Defined*.

In addition to Regev and Wegmann's goal types, Asnar et al. [7] proposed a framework for understanding and mitigating the risks of events that affect goal satisfaction when selecting between alternative designs (within the Tropos framework). Using KAOS, Letier et al. [11] considered goals that are real-time timing properties of a system and developed a formal approach to construct software specifications from these goals.

Printing IStar Model: Loan Example - Assess Application Sub-model

```

Intentions:
ID  Name Type Value
0   Assess Application   OI  2
1   Assessed In-house   AI  0
2   Assessed by Credit Bureau AI  2
3   Receive Assessments MP  2
4   Receive Quality Assessments MP  2
5   Determine AssessmentsNT 0
6   Build Assessment System MP  0
7   Produce Quality Assessments MP  2
8   Understand Monetary Conditions MP  2
9   Audit Assessments Procedures MP  0
Intention Links:
Name Type Source Target
- OR Assessed In-house Assess Application
- OR Assessed by Credit Bureau Assess Application
- AND Receive Assessments Assessed by Credit Bureau
- AND Receive Quality Assessments Assessed by Credit Bureau
- AND Determine Assessments Assessed In-house
- AND Build Assessment System Determine Assessments
- AND Produce Quality Assessments Assessed In-house
- MAKE Understand Monetary Conditions Produce Quality Assessments
- HELP Audit Assessments Procedures Produce Quality Assessments

```

Would you like to (a) interrupt after every Epoch, (b) set a breakpoint, (w) watch a variable, (v) change a value, (f) run the full simulation?  
Performing analysis now:

ID	0	1	2	3	4	5	6	7	8	9
Type	OI	AI	AI	MP	MP	NT	MP	MP	MP	MP
0	2	0	2	2	2	0	0	2	2	0
1	2	1	2	3	2	1	1	1	2	1
2	3	1	3	3	3	1	1	2	3	1
3	3	2	3	3	3	2	2	3	3	2
4	3	2	3	4	3	2	2	4	4	2
5	4	2	4	4	4	2	2	4	4	2

Assess by Credit Bureau Satisfied.

Assess Application Satisfied. (Short-term)

Type	OI	AI	AI	MP	R	NT	MP	MP	MP	MP
- simulation lines removed for simplicity -										
17	3	3	3	3	2	4	4	3	3	3
18	3	3	3	4	3	4	4	3	3	3
19	3	3	1	4	1	4	4	3	3	3
20	4	4	1	4	1	4	4	4	4	4

Assess by Credit Bureau Satisfied.

Assess Application Satisfied. (Long-term)

ID	53	4	4	4	4	4	4	4	4	4
Type	OI	AI	AI	MP	R	NT	MP	MP	MP	MP

Finished analysis now. Assess Application Satisfied.

Short-term result recommendation: Assessed by Credit Bureau.

Long-term result recommendation: Assessed In-house.

Fig. 4. Sample output of the simulator showing the evaluation of the intentions and goals at various time points.

They defined the goals in temporal logic and connected timed event-based models [12] with state-based formalisms. In our work, we look at the evolution of goals in the model rather than looking at concrete timing requirements, or concrete events within the model. The propagation delays in our system are not explicit measurable time delays; they are left unspecified to allow for uncertainty in the model. We use a simple constraint language rather than temporal logic to reduce the complexity of our static analysis and simulation. Cheong and Winikoff [13] focused on connecting time dependent goals within a decomposition (denoted by precondition links), allowing for the coordination and achievement of agents' plans. Gans et al. [14] add temporal ordering to  $i^*$  models in order to simulate goal alternatives. We use relative or ordered dependency constraints specified by the modeler, which is similar to Cheong and Winikoff.

Goals as dynamic entities have been used outside the requirements phase for runtime analysis [15] [16], self-adaptive systems [17], and context-aware systems [18]. Dalpiaz et al. distinguished between design-time goal models and runtime goal models [19]. Throughout our simulation and analysis,

our models remain design-time goal models at the class level. Robinson et al. [15] convert goal models into components that monitor states in the system through runtime monitoring. Baresi et al. [17] add adaptive goals to goal models in monitoring the system at runtime. These do not monitor how the requirements in the model change, but rather monitor properties of the system.

In terms of how propagation impacts goals, we have discussed using forward analysis (a bottom-up approach) with qualitative evaluation. Others have developed and used complementary approaches [2] [4] [20]. Our analysis techniques could be adapted for quantitative analysis (as in [3] [4] [5]) or hybrid analysis (as in [20]). We have yet to investigate applying our technique to backward analysis (a top-down approach) [4] [8], but see this as useful and complementary to forward analysis.

## VI. CONCLUSIONS & FUTURE WORK

In this position paper, we introduced dynamic intentions for goal models as well as dynamic function types with the goal of modeling alternatives on multiple time scales. We believe that goal model analysis for early phase requirements can be improved by explicitly considering these dynamics. We presented a framework for doing both static analysis and simulation of dynamic intentions and explored the technique through an example of a bank entering the loan market deciding whether to assess loan applications in-house or outsource the assessments to a credit agency.

In future work, we will complete our simulator for analysis across points and implement the *Static Analysis* component. Once we have validated our methodology on the qualitative analysis of  $i^*$ , we will then investigate how it can be incorporated into quantitative and hybrid analysis techniques presented in other goal modeling languages.

## VII. ACKNOWLEDGEMENTS

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